

**Web-based Supplementary Materials for**  
**“A space-time conditional intensity model**  
**for invasive meningococcal disease occurrence”**

by

**Sebastian Meyer<sup>1,2</sup>, Johannes Elias<sup>3</sup>, and Michael Höhle<sup>4,2</sup>**

<sup>1</sup>Department of Psychiatry and Psychotherapy, Ludwig-Maximilians-Universität, München, Germany

<sup>2</sup>Department of Statistics, Ludwig-Maximilians-Universität, München, Germany

<sup>3</sup>German Reference Centre for Meningococci, University of Würzburg, Würzburg, Germany

<sup>4</sup>Department for Infectious Disease Epidemiology, Robert Koch Institute, Berlin, Germany

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## Web Appendix A: Calculus of the Score Function

Let  $\boldsymbol{\vartheta}$  denote any subvector of  $\boldsymbol{\theta}$ . Then, the partial derivative of the log-likelihood with respect to  $\boldsymbol{\vartheta}$  is

$$\mathbf{s}_{\boldsymbol{\vartheta}}(\boldsymbol{\theta}) := \frac{\partial}{\partial \boldsymbol{\vartheta}} l(\boldsymbol{\theta}) = \sum_{i=1}^n \frac{\frac{\partial}{\partial \boldsymbol{\vartheta}} \lambda_{\boldsymbol{\theta}}^*(t_i, \mathbf{s}_i, \kappa_i)}{\lambda_{\boldsymbol{\theta}}^*(t_i, \mathbf{s}_i, \kappa_i)} - \int_0^T \int_W \sum_{\kappa \in \mathcal{K}} \frac{\partial}{\partial \boldsymbol{\vartheta}} \lambda_{\boldsymbol{\theta}}^*(t, \mathbf{s}, \kappa) dt d\mathbf{s}, \quad (1)$$

and the score function is  $\mathbf{s}(\boldsymbol{\theta}) = \frac{\partial}{\partial \boldsymbol{\theta}} l(\boldsymbol{\theta}) = (\mathbf{s}'_{\beta_0}, \mathbf{s}'_{\beta}, \mathbf{s}'_{\gamma}, \mathbf{s}'_{\sigma}, \mathbf{s}'_{\alpha})'(\boldsymbol{\theta})$ . The necessary partial derivatives of the CIF with their respective time-space-mark integrals are given in the following subsections and can be plugged into the equation (1). The analytic derivatives of the interaction function  $f$  and  $g$  with respect to  $\boldsymbol{\sigma}$  and  $\boldsymbol{\alpha}$ , respectively, have to be determined for the specific model at hand. For instance, a type-specific spatial Gaussian kernel

$$f_{\boldsymbol{\sigma}}(\mathbf{s}|\kappa) = \exp\left(-\frac{\|\mathbf{s}\|^2}{2\sigma_{\kappa}^2}\right)$$

with  $\boldsymbol{\sigma} = (\sigma_1, \dots, \sigma_K)'$  has partial derivatives

$$\frac{\partial}{\partial \sigma_k} f_{\boldsymbol{\sigma}}(\mathbf{s}|\kappa) = \mathbb{1}_{k=\kappa}(\kappa) \cdot \exp\left(-\frac{\|\mathbf{s}\|^2}{2\sigma_k^2}\right) \frac{\|\mathbf{s}\|^2}{\sigma_k^3}, \quad \text{for any } k \in \mathcal{K}.$$

The type-specific temporal interaction function  $g_{\boldsymbol{\alpha}}(t|\kappa) = e^{-\alpha_{\kappa} t}$  with  $\boldsymbol{\alpha} = (\alpha_1, \dots, \alpha_K)$  has partial derivatives  $\frac{\partial}{\partial \alpha_k} g_{\boldsymbol{\alpha}}(t|\kappa) = \mathbb{1}_{k=\kappa}(\kappa) \cdot (-t e^{-\alpha_k t})$ , for any  $k \in \mathcal{K}$ . While the integral of  $\frac{\partial}{\partial \sigma_k} f_{\boldsymbol{\sigma}}(\mathbf{s}|\kappa)$  over the region  $R_j$  will be approximated by numerical integration, the temporal function  $\frac{\partial}{\partial \alpha_k} g_{\boldsymbol{\alpha}}(t|\kappa)$  is assumed to permit analytical integration.

**Endemic intercept(s)  $\beta_0$ :**

Let  $\beta_{0,k}$ ,  $k \in \{1, \dots, K\}$  be one of the type-specific intercepts in  $\beta_0$ . Then,

$$\frac{\partial}{\partial \beta_{0,k}} \lambda_{\theta}^*(t, \mathbf{s}, \kappa) = \mathbb{1}_{k=\kappa}(\kappa) \cdot \exp \left( \beta_{0,k} + o_{\xi(s)} + \boldsymbol{\beta}' \mathbf{z}_{\tau(t), \xi(s)} \right)$$

since the parameter  $\beta_{0,k}$  appears in the endemic component  $h_{\theta}(t, \mathbf{s}, \kappa)$  if and only if  $\kappa = k$ . The corresponding integrated value is

$$\int_0^T \int_W \sum_{\kappa \in \mathcal{K}} \frac{\partial}{\partial \beta_{0,k}} \lambda_{\theta}^*(t, \mathbf{s}, \kappa) dt d\mathbf{s} = e^{\beta_{0,k}} \cdot \sum_{\tau=1}^D \sum_{\xi=1}^M |C_{\tau}| |A_{\xi}| \exp(o_{\xi} + \boldsymbol{\beta}' \mathbf{z}_{\tau, \xi}) ,$$

cf. the integral of the endemic component in equation (6) of the paper. If the model assumes a type-invariant endemic intercept  $\beta_0 = \beta_0$ , then

$$\frac{\partial}{\partial \beta_0} \lambda_{\theta}^*(t, \mathbf{s}, \kappa) = \exp \left( \beta_0 + o_{\xi(s)} + \boldsymbol{\beta}' \mathbf{z}_{\tau(t), \xi(s)} \right)$$

with integrated value

$$\int_0^T \int_W \sum_{\kappa \in \mathcal{K}} \frac{\partial}{\partial \beta_0} \lambda_{\theta}^*(t, \mathbf{s}, \kappa) dt d\mathbf{s} = K e^{\beta_0} \cdot \sum_{\tau=1}^D \sum_{\xi=1}^M |C_{\tau}| |A_{\xi}| \exp(o_{\xi} + \boldsymbol{\beta}' \mathbf{z}_{\tau, \xi}) .$$

**Endemic covariate effects  $\beta$ :**

$$\frac{\partial}{\partial \boldsymbol{\beta}} \lambda_{\theta}^*(t, \mathbf{s}, \kappa) = \exp \left( \beta_0(\kappa) + o_{\xi(s)} + \boldsymbol{\beta}' \mathbf{z}_{\tau(t), \xi(s)} \right) \cdot \mathbf{z}_{\tau(t), \xi(s)}$$

with corresponding integral vector (element-wise integral values)

$$\left( \sum_{\kappa \in \mathcal{K}} \exp(\beta_0(\kappa)) \right) \cdot \sum_{\tau=1}^D \sum_{\xi=1}^M |C_{\tau}| |A_{\xi}| \exp(o_{\xi} + \boldsymbol{\beta}' \mathbf{z}_{\tau, \xi}) \mathbf{z}_{\tau, \xi} .$$

**Epidemic effects  $\gamma$ :**

$$\frac{\partial}{\partial \gamma} \lambda_{\theta}^*(t, \mathbf{s}, \kappa) = \sum_{j \in I^*(t, \mathbf{s}, \kappa)} e^{\gamma' \mathbf{m}_j} g_{\alpha}(t - t_j | \kappa_j) f_{\sigma}(\mathbf{s} - \mathbf{s}_j | \kappa_j) \mathbf{m}_j,$$

and the corresponding integral can be deduced similar to equation (7) of the paper as

$$\sum_{j=1}^n q_{\kappa_j, \bullet} e^{\gamma' \mathbf{m}_j} \left[ \int_0^{\min\{T-t_j; \varepsilon\}} g_{\alpha}(t | \kappa_j) dt \right] \left[ \int_{R_j} f_{\sigma}(\mathbf{s} | \kappa_j) d\mathbf{s} \right] \mathbf{m}_j.$$

**Parameters  $\sigma$  and  $\alpha$  of the interaction functions:**

For a general spatial kernel  $f_{\sigma}(\mathbf{s} | \kappa)$ ,

$$\frac{\partial}{\partial \sigma} \lambda_{\theta}^*(t, \mathbf{s}, \kappa) = \sum_{j \in I^*(t, \mathbf{s}, \kappa)} e^{\eta_j} g_{\alpha}(t - t_j | \kappa_j) \left[ \frac{\partial}{\partial \sigma} f_{\sigma}(\mathbf{s} - \mathbf{s}_j | \kappa_j) \right]$$

with corresponding integral

$$\sum_{j=1}^n q_{\kappa_j, \bullet} e^{\eta_j} \left[ \int_0^{\min\{T-t_j; \varepsilon\}} g_{\alpha}(t | \kappa_j) dt \right] \left[ \int_{R_j} \frac{\partial}{\partial \sigma} f_{\sigma}(\mathbf{s} | \kappa_j) d\mathbf{s} \right].$$

Similarly, for a general temporal kernel  $g_{\alpha}(t | \kappa)$ ,

$$\frac{\partial}{\partial \alpha} \lambda_{\theta}^*(t, \mathbf{s}, \kappa) = \sum_{j \in I^*(t, \mathbf{s}, \kappa)} e^{\eta_j} \left[ \frac{\partial}{\partial \alpha} g_{\alpha}(t - t_j | \kappa_j) \right] f_{\sigma}(\mathbf{s} - \mathbf{s}_j | \kappa_j)$$

with corresponding integral

$$\sum_{j=1}^n q_{\kappa_j, \bullet} e^{\eta_j} \left[ \int_0^{\min\{T-t_j; \varepsilon\}} \frac{\partial}{\partial \alpha} g_{\alpha}(t | \kappa_j) dt \right] \left[ \int_{R_j} f_{\sigma}(\mathbf{s} | \kappa_j) d\mathbf{s} \right].$$

## Web Appendix B: Fisher Information Matrix

The inverse of the Fisher information matrix at the maximum likelihood estimate (MLE)  $\hat{\boldsymbol{\theta}}_{ML}$  is in general likelihood theory used as an estimate of the variance of  $\hat{\boldsymbol{\theta}}_{ML}$ . The precise conditions under which asymptotic properties of MLEs hold for spatio-temporal point processes have been established by Rathbun (1996). Specifically, the conditions for existence, consistence and asymptotic normality of a local maximum  $\hat{\boldsymbol{\theta}}_{ML}$  as  $T \rightarrow \infty$  for a fixed observation region  $W$  are discussed in Meyer (2009, Section 4.2.3).

The expected Fisher information  $\mathcal{I}(\boldsymbol{\theta})$  can be estimated by the “optional variation process” adapted to the marked spatio-temporal setting (Rathbun, 1996, equation (4.7))

$$\int_0^T \int_W \int_{\mathcal{K}} \left( \frac{\partial}{\partial \boldsymbol{\theta}} \log \lambda_{\boldsymbol{\theta}}^*(t, \mathbf{s}, \kappa) \right)^{\otimes 2} dN(t, \mathbf{s}, \kappa)$$

through its observed realisation

$$\hat{\mathcal{I}}(\boldsymbol{\theta}) = \sum_{i=1}^n \left( \frac{\partial}{\partial \boldsymbol{\theta}} \log \lambda_{\boldsymbol{\theta}}^*(t_i, \mathbf{s}_i, \kappa_i) \Big|_{\tilde{\boldsymbol{\theta}}=\boldsymbol{\theta}} \right)^{\otimes 2} = \sum_{i=1}^n \left( \frac{\frac{\partial}{\partial \boldsymbol{\theta}} \lambda_{\boldsymbol{\theta}}^*(t_i, \mathbf{s}_i, \kappa_i)}{\lambda_{\boldsymbol{\theta}}^*(t_i, \mathbf{s}_i, \kappa_i)} \Big|_{\tilde{\boldsymbol{\theta}}=\boldsymbol{\theta}} \right)^{\otimes 2},$$

where  $\mathbf{a}^{\otimes 2} := \mathbf{a}\mathbf{a}'$  for a vector  $\mathbf{a}$ . Uncertainty of the parameter estimates is thus deduced from the diagonal of  $\hat{\mathcal{I}}^{-1/2}(\hat{\boldsymbol{\theta}}_{ML})$ , which contains their standard errors.

## References

- Meyer, S. (2009). Spatio-temporal infectious disease epidemiology based on point processes. Master’s thesis, Department of Statistics, Ludwig-Maximilians-Universität, München. Available as <http://epub.ub.uni-muenchen.de/11703/>.
- Rathbun, S. L. (1996). Asymptotic properties of the maximum likelihood estimator for spatio-temporal point processes. *Journal of Statistical Planning and Inference* **51**, 55–74.

## Web Appendix C: Simulation Algorithm

This appendix provides a more implementational view on the simulation algorithm described in Section 4 of the paper. In addition to the notation of the paper, let  $L(t)$  be the next time point after time  $t$  where any endemic covariate in any tile changes its value, or a previously infected individual stops spreading the disease, i.e.:

$$L(t) = \min \{t' > t \mid (\exists \xi \in \{1, \dots, M\} : z_{\tau(t'), \xi} \neq z_{\tau(t), \xi}) \vee (\exists j \in \{1, \dots, N_g(t)\} : t' = t_j + \varepsilon)\}.$$

An implementational perspective on the simulation algorithm is then:

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### Algorithm 1: Ogata's modified thinning adapted for `twinstim`

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- 1 Given current time  $t$ , update  $L(t)$  and calculate local upper bound  $\bar{\lambda}_g^*(t)$ ;
  - 2 Generate proposed waiting time  $\Delta \sim \text{Exp}(\bar{\lambda}_g^*(t))$ ;
  - 3 **if**  $t + \Delta > L(t)$  **then**
  - 4     | Let  $t = L(t)$ ;
  - 5 **else**
  - 6     | Let  $t = t + \Delta$ ;
  - 7     | Accept  $t$  with probability  $\lambda_g^*(t)/\bar{\lambda}_g^*(t)$ , otherwise goto step 1;
  - 8     | Draw the source of infection (infective individual  $j$  or endemic) with weights equal to the respective components of  $\lambda_g^*(t)$  (cf. equation (8) of the paper);
  - 9     | **if** *endemic source of infection* **then**
  - 10         | Draw the type  $\kappa$  of the new event with weights  $\exp(\beta_0(\kappa))$ ,  $\kappa \in \mathcal{K}$ ;
  - 11         | Draw the tile  $A_\xi$  of the new event with weights  $|A_\xi| \rho_{\tau(t), \xi} e^{\beta' z_{\tau(t), \xi}}$ ,  $\xi \in \{1, \dots, M\}$ ;
  - 12         | Draw the location  $s$  of the new event uniform within the sampled tile  $A_\xi$ ;
  - 13     | **else**
  - 14         | Draw the type  $\kappa$  of the new event at random out of the types which can be triggered by the source individual  $j$ , i.e. draw from  $U(\{\kappa \in \mathcal{K} : q_{\kappa_j, \kappa} = 1\})$ ;
  - 15         | Draw the relative location  $v$  of the new event (relative to the source  $j$ ) from the density  $f(s|\kappa_j)/\int_{R_j} f(s|\kappa_j) ds$  on  $R_j$ , i.e.  $s = s_j + v$ ;
  - 16     | Draw additional marks according to the pre-specified distribution;
  - 17     | Update the event history;
  - 18 Goto step 1;
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An R implementation of the algorithm can be found as the function `simEpidataCS` in the popular `surveillance` package.