

# AN APPROXIMATION THEOREM FOR MAPS INTO KAN FIBRATIONS

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In this note we prove that a semisimplicial map into the base of a Kan fibration having a continuous lifting to the total space also has a semisimplicial lifting, very "close" to a given continuous lifting. As a special case we obtain a new proof of the famous Milnor-Lamotke theorem that a Kan set is a strong deformation retract of the singular set of its geometric realization.

First we state our main

**THEOREM.** *Let*

$$( \ast ) \quad \begin{array}{ccc} X & \xrightarrow{f} & E \\ i \downarrow & & \downarrow p \\ Y & \xrightarrow{h} & B \end{array}$$

be a commutative square in the category of semisimplicial sets with  $i$  an inclusion and  $p$  a Kan fibration. Further, suppose given a continuous  $\bar{g}: |Y| \rightarrow |E|$  with  $\bar{g} \circ i = f$  and  $|p| \circ \bar{g} = h$ . Then there exists a homotopy  $\bar{g} \cong g'$  rel.  $|X|$  and over  $|B|$  so that  $g' = |g|$  for some semisimplicial  $g$ .

This theorem has an interesting special case. Take  $X = E$  a Kan set,  $Y = S|E|$ ,  $B$  a point,  $p, h$  the unique constant maps,  $f = id_E$ ,  $i$  the natural inclusion and  $\bar{g}$  the natural retraction. What comes out is the famous Milnor-Lamotke theorem saying  $E$  is strong deformation retract of  $S|E|$ . Thus we get a new proof of this theorem which in contrast to the original one [4] avoids any reference to J.H.C. Whitehead's theorems.

On the other hand, if  $B$  is a point, the statement is a trivial consequence of the Milnor-Lamotke theorem. An elementary proof for this case—avoiding the Milnor-Lamotke theorem—has been given by B. J. Sanderson [7] whose techniques are also important for our proceeding.

*Proof of theorem.* (For the technical details we use the notation explained in §0 of [1].) By an induction over skeletons, it is enough

to prove the theorem in the case  $y$  is an  $n$ -simplex  $\Delta[n]$  with  $n > 0$  and  $X$  is its boundary  $\partial\Delta[n]$ . Let  $\epsilon$  be the generating simplex of  $\Delta[n]$ ,  $y = h\epsilon \in B$  and  $\bar{y} = Sg(\epsilon) \in S|E|$ . We have to prove that  $\bar{y}$  is  $S|B|$ -equivalent ([3] p. 123) to a simplex in  $E^1$ .

Decompose  $y = y^+y^0$  with  $y^+$  nondegenerate and  $y^0$  surjective. We perform a further induction, over a (partial) ordering of the set of the possible  $y^0$ , that is the set  $D_n$  of surjective monotone maps with domain  $[n]$ . Choose<sup>2</sup> an ordering of this set satisfying (i) and (ii):

(i)  $\beta\alpha \leq \alpha$  if  $\alpha, \beta\alpha \in D_n$ ; and

(ii) each nonconstant  $\alpha \in D_n$  admits an  $\alpha' < \alpha$  so that  $\alpha'$  is the surjective part of  $\alpha\sigma_i\delta_j$  for some suitable pair  $i, j$ .

Evidently the constant map is the minimum of  $D_n$  with respect to this ordering.

First, assume  $y^0$  is constant. Denote by  $F$  the fibre over  $y$  which is Kan. Now comes Sanderson's idea. Since the boundary of  $\bar{y}$  belongs to  $F$  we can choose the zeroth vertex \* of  $\bar{y}$  for base point of  $F$ . Then, form the path fibration  $q: W(F) \rightarrow F$  ([5] p. 196) and lift  $\bar{y}$  to a filling  $\bar{u}$  in  $S|W(F)|$  of the horn  $(-, \bar{y}\delta_1\sigma_0, \dots, \bar{y}\delta_n\sigma_0)$  in  $W(F) \subset S|W(F)|$ . By induction,  $\bar{u}\delta_0$  is  $S|F|$ -equivalent to an  $u \in W(F)$ . That gives a  $\bar{z} \in S|W(F)|$  with boundary  $(u, \bar{u}\delta_0, u\sigma_0\delta_2, \dots, u\sigma_0\delta_n)$  and  $S|q|\bar{z} = \bar{y}\delta\sigma_0 \in F$  ([5] p. 25). Next we use that every sphere in  $W(F)$  can be filled ([5] p. 196) and also every sphere in  $S|W(F)|$  since  $W(F)$  is contractible. Take a filling  $v \in W(F)$  of the sphere  $(u, \bar{y}\delta_1\sigma_0, \dots, \bar{y}\delta_n\sigma_0)$  and finally a filling  $\bar{v} \in S|W(F)|$  of the sphere  $(\bar{z}, v, \bar{u}, \bar{z}\sigma_0\delta_3, \dots, \bar{z}\sigma_0\delta_{n+1})$ . Then  $S|q|\bar{v}$  is an  $S|B|$ -equivalence between  $\bar{y}$  and  $qv \in F \subset E$ .

If  $y^0$  is not constant, we choose  $i$  and  $j$  such that the surjective part of  $y^0\sigma_i\delta_j$  is less than  $y^0$ . Set  $\epsilon = 0$  if  $j < i$  and  $\epsilon = 1$  if  $j > i + 1$ . Lift  $y$  to  $u \in E$  with  $u\delta_k = \bar{y}\delta_k$  if  $k \neq j - \epsilon$  and lift  $y\sigma_i$  to  $\bar{u} \in S|E|$  with  $\bar{u}\delta_i = \bar{y}$ ,  $\bar{u}\delta_{i+1} = u$ ,  $\bar{u}\delta_k = \bar{y}\sigma_i\delta_k$  if  $k \neq i, i + 1, j$ . By induction,  $\bar{u}\delta_j$  is  $|B|$ -equivalent to a  $v \in E$  and there is a  $\bar{v} \in S|E|$  with boundary  $(v\sigma_{i+\epsilon}\delta_0, \dots, v, \bar{u}\delta_j, \dots, v\sigma_{i+\epsilon}\delta_{n+1})$  and  $S|p|\bar{v} = y\sigma_i\sigma_{i+1}\delta_{j+\epsilon}$ . Next, lift  $y\sigma_i$  to  $w \in E$  with  $w\delta_{i+1} = u$ ,  $w\delta_j = v$ ,  $w\delta_k = \bar{y}\sigma_i\delta_k$  if  $k \neq i, i + 1, j$  and lift  $y\sigma_i\sigma_{i+1}$  to  $\bar{w}$  with  $\bar{w}\delta_{i+1} = w$ ,  $\bar{w}\delta_{i+2} = \bar{u}$ ,  $\bar{w}\delta_{j+\epsilon} = \bar{v}$ ,  $\bar{w}_k = w\sigma_{i+\epsilon}\delta_k$  if  $k \neq i, i + 1, i + 2, j + \epsilon$ . Then  $\bar{w}\delta_i$  is an  $S|B|$ -equivalence between  $\bar{y}$  and  $w\delta_i \in E$ .

This finishes the proof. As an application, we'll derive a streng-

<sup>1</sup> Note that  $S|p|$  is also a Kan fibration, by Quillen's result [6].

<sup>2</sup> Cf. the proof of Lemma 4 in [2].

thening of this result which is based on the cartesian closedness of the category of semisimplicial sets. Roughly speaking, it states the semisimplicial set of semisimplicial diagonals of a square as in the theorem is a strong deformation retract of the semisimplicial set of its continuous diagonals.

To make this precise, we define the *semisimplicial set*  $D(Y, E)$  of (semisimplicial) diagonals of a square (\*) by means of the following diagram where the squares involved are pullbacks

$$\begin{array}{ccccc}
 & & D(Y, E) & & \\
 & \searrow & & \swarrow & \\
 & \bullet & & \bullet & \\
 \swarrow & & \searrow & & \swarrow \\
 A[0] & & E^Y & & Z[0] \\
 \downarrow f & \searrow E^i & \downarrow p^Y & \searrow h & \\
 E^X & & B^Y & &
 \end{array}$$

Further, the semisimplicial set of continuous diagonals of (\*) is defined to be the semisimplicial set  $D(Y, S|E|)$  of semisimplicial diagonals of the square

$$\begin{array}{ccc}
 X & \xrightarrow{i_E \circ f} & S|E| \\
 i \downarrow & & \downarrow S|p| \\
 Y & \xrightarrow{i_B \circ h} & S|B|
 \end{array}$$

The following lemma gives another description of  $D(Y, S|E|)$ .

**LEMMA.** *Let*

$$\begin{array}{ccc}
 \bar{E} & \longrightarrow & S|E| \\
 \bar{p} \downarrow & & \downarrow S|p| \\
 B & \xrightarrow{i_B} & S|\bar{B}|
 \end{array}$$

*be a pullback. Then the semisimplicial set  $D(Y, \bar{E})$  of diagonals of the induced square*

$$\begin{array}{ccc} X & \xrightarrow{\bar{f}} & E \\ i \downarrow & & \downarrow \bar{p} \\ Y & \xrightarrow{h} & B \end{array}$$

is isomorphic to  $D(Y, S|E|)$ .

The proof of this lemma is evident. Note the universal property of  $\bar{E}$ : The continuous  $\bar{g}: |Y| \rightarrow |E|$  so that  $|p| \circ \bar{g}$  is realized correspond bijectively to the semisimplicial maps  $Y \rightarrow \bar{E}$ . If  $B$  is a point, this is the adjunction between geometric realization and singular functor.

With these definitions we have the

**COROLLARY.** *Under the assumptions of the theorem on the square (\*)  $D(Y, E)$  is a strong deformation retract of  $D(Y, \bar{E})$ .*

*Proof.* The map  $|\bar{E}| \rightarrow |E|$  corresponding to  $\text{id}\bar{E}$  is a continuous diagonal of the square

$$\begin{array}{ccc} E & \xrightarrow{\text{id}E} & E \\ \downarrow & & \downarrow p \\ \bar{E} & \longrightarrow & B \end{array}$$

Thus, the theorem implies  $E$  is a strong deformation retract of  $\bar{E}$ . Let  $G: \bar{E} \times \Delta[1]$  be a suitable deformation. Further, let  $e$  denote the evalution  $Y \times \bar{E}^Y \rightarrow \bar{E}$  and  $\text{id}\bar{E}$ . Then, by adjointness  $G \circ e$  corresponds to a map  $K: \bar{E}^Y \times \Delta[1] \rightarrow \bar{E}^Y$ . Its restriction to  $D(Y, \bar{E}) \times \Delta[1]$  factors through  $D(Y, E)$  and induces a deformation of the desired kind.

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