



Data generation for composite-based structural equation modeling methods

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Abstract

Examining the efficacy of composite-based structural equation modeling (SEM) features prominently in research. However, studies analyzing the efficacy of corresponding estimators usually rely on factor model data. Thereby, they assess and analyze their performance on erroneous grounds (i.e., factor model data instead of composite model data). A potential reason for this malpractice lies in the lack of available composite model-based data generation procedures for prespecified model parameters in the structural model and the measurements models. Addressing this gap in research, we derive model formulations and present a composite model-based data generation approach. The findings will assist researchers in their composite-based SEM simulation studies.

Keywords Composite models · Data generation · Generalized structural component analysis · GSCA · Partial least squares · PLS · Structural equation modeling · SEM

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1 Introduction

Research in the social sciences often involves inference about concepts such as attitudes, perceptions, and behavioral intentions. Since such concepts cannot be measured directly, observed variables (also referred to as indicators) are used to represent them as latent variables (or constructs) in statistical models. Structural equation modeling (SEM) has become the standard tool to validate the indirect measurement of unobservable concepts and analyze complex interrelations between latent variables. Researchers can choose from two conceptually different approaches to SEM: factor- and composite-based SEM (Jöreskog and Wold 1982; Rigdon et al. 2017).

In factor-based SEM unobservable conceptual variables are approximated by common factors under the assumption that each latent variable exists as an entity independent of observed variables. This latent variable serves as the sole source of the associations among the observed variables. That is, when controlling for the impact of the latent variable, the indicator correlations are zero. One of the first and most prominent formulations of factor-based SEM has been established by Jöreskog (1978). On the contrary, composite-based SEM represents latent variables by weighted composites of observed variables, assuming each one to be an aggregation of observed variables (Sarstedt et al. 2016). Although many methods fall into the domain of composite-based SEM, partial least squares (PLS; Lohmöller 1989; Wold 1982) and generalized structured component analysis (GSCA; Hwang and Takane 2004) constitute the most advanced and frequently used approaches in the field (Hwang et al. 2020; Hwang and Takane 2014).

As factor- and composite-based SEM both try to achieve the same aim – estimating a series of structural equations that represent causal processes – researchers have routinely compared their relative efficacy on the grounds of simulated data (Rigdon et al. 2017). However, the studies usually have evaluated composite-based SEM methods on the grounds of factor model data, where the indicator covariances define the nature of the data (Sarstedt et al. 2016). These studies univocally show that composite-based SEM methods produce biased results that typically manifest themselves in measurement model parameters (i.e., indicator loadings and weights) being overestimated and structural model parameters being underestimated (Goodhue et al. 2012; Lu et al. 2011; Reinartz et al. 2009). However, these results are not considering that the estimated models were misspecified with regard to the data generation process in the simulation studies—as noted by numerous authors (Marcoulides et al. 2012; Rigdon 2012; Rigdon et al. 2017).¹

In fact, very few simulation studies have assessed composite-based SEM using data that are consistent with the assumptions of the method. We believe that the reason for the scarcity of research in this field lies in the lack of suitable data generation procedures. Specifically, while the data generation process for factor-based SEM is well documented and frequently discussed in the literature (e.g., Reinartz et al. 2002), this is

¹ The concepts of factor and composite model data need to be differentiated from reflective and formative measurement, which refers to the theoretical specification of the constructs on the grounds of measurement theory (Sarstedt et al. 2016). Regardless of whether researchers use reflective or indicators, composite-based SEM methods always compute weighted composites of observed variables to represent conceptual variables in the statistical model (Hwang et al. 2020).

not the case with composite-based SEM. Generating data for composite-based simulation studies in an SEM context is challenging because the size of the path coefficients, which define the strength of relationships between latent variables, are inextricably tied to the target variable's coefficient of determination. A composite model-based data generating process must consider such dependencies. Even though needed for simulation studies, corresponding procedures have remained nontransparent.

Our research seeks to fill this gap by discussing the specification of covariance matrices in composite-based data generation, which can serve as input for simulation studies. Our approach allows researchers to generate data for composite models with pre-specified indicator weights and path coefficients or coefficients of determination to assess the method's efficacy. The package `cbsem` (Schlittgen 2019) of the statistical software R (R Core Team 2019) contains all functions described in the further course of this article.

2 The composite-based model

Consider two sets of indicator variables, $\mathbf{x} = (X_1, \dots, X_{p_1})$ and $\mathbf{y} = (Y_1, \dots, Y_{p_2})$, whereby all the variables should be standardized, $E(X_i) = 0$ and $\text{Var}(X_i) = 1$; the same applies to Y_i . The relationships between these two sets of variables are modelled using composites in the structural model.² The independent composites ξ use \mathbf{x} as indicators in their measurement models, whereas the dependent composites η employ the indicators \mathbf{y} . Independent composites do not depend on any other composite in the structural model. Each of the composites η , which result from the \mathbf{y} indicator variables, is dependent and, as such, is regressed on at least one other composite, regardless of whether it is an independent composite ξ or another dependent composite η . The number of independent composites is q_1 , while the number of dependent composites is q_2 .

The measurement models allow to determine the composites of the structural model (i.e., their scores) by using a specific set of observed variables as indicators for each composite. Linear combinations of the \mathbf{x} and \mathbf{y} indicator variables generate the scores of each composite. The indicators of ξ_g build a subvector \mathbf{x}_g of \mathbf{x} , $g = 1, \dots, q_1$. The corresponding weights vectors are denoted by $\mathbf{w}_g^{(1)}$. η_h has indicators \mathbf{y}_h with weights $\mathbf{w}_h^{(2)}$, $h = 1, \dots, q_2$. The parameter vectors are column vectors whereas the random vectors are row vectors. This formal representation is not very common but has the advantage that the equations have the same appearance as the corresponding data matrices' relations. The weights relations are (Semadeni et al. 2014):

$$\xi = \mathbf{x}\mathbf{W}_1, \quad (1a)$$

$$\eta = \mathbf{y}\mathbf{W}_2, \quad (1b)$$

² In the following, we refer to composites rather than latent variables to denote entities that are conceptual variables in a statistical model.

with

$$W_1 = \begin{pmatrix} w_1^{(1)} & \mathbf{0} & \dots & \mathbf{0} \\ \mathbf{0} & w_2^{(1)} & & \mathbf{0} \\ \vdots & & & \vdots \\ \mathbf{0} & \mathbf{0} & \dots & w_{q_1}^{(1)} \end{pmatrix}, \quad W_2 = \begin{pmatrix} w_1^{(2)} & \mathbf{0} & \dots & \mathbf{0} \\ \mathbf{0} & w_2^{(2)} & & \mathbf{0} \\ \vdots & & & \vdots \\ \mathbf{0} & \mathbf{0} & \dots & w_{q_2}^{(2)} \end{pmatrix}. \tag{1c}$$

The composites have unit variances, $\text{Var}(\xi_g) = 1$ and $\text{Var}(\eta_h) = 1$. This implies that the weights are standardized, $w_g^{(1)'} \Sigma_{x_g x_g} w_g^{(1)} = 1$ where $\Sigma_{x_g x_g}$ is the population indicators' matrix of block g . The same applies to $w_h^{(2)}$.

While the measurement models determine the composites using the weights W_1 and W_2 , the structural model provides the relationships between the two sets of indicators by means of the resulting two sets of composites:

$$\eta = \xi \Gamma' + \eta \mathbf{B}' + \zeta, \tag{2}$$

The matrix \mathbf{B} can be arranged as a lower triangular with zeros on the diagonal for recursive models, which applies here; ζ is a vector of errors, whereby the errors are presumed to be uncorrelated and also uncorrelated in respect of the other random vectors. The formulation with row vectors implies that the transposes of Γ and \mathbf{B} appear in Eq. (2). The path coefficients in Γ and \mathbf{B} are the parameters of primary interest. They describe the composites' interrelations. From the structural model's recursiveness, it follows that $(\mathbf{I} - \mathbf{B}')$ is regular and a reduced form of Equation (2) exists:

$$\eta = \xi \Gamma' (\mathbf{I} - \mathbf{B}')^{-1} + \zeta (\mathbf{I} - \mathbf{B}')^{-1}. \tag{3}$$

3 The covariance matrix of the composites

Establishing the covariance matrix of a path model with composites requires determining the main parameters. In the structural model, these include (a) the path coefficients, (b) the independent composites' correlations, and (c) the dependent composites' coefficients of determination; in the measurement model, the relevant parameters are (d) the weights.

The specification of the path coefficients and the coefficients of determination are interrelated. When path coefficients are of primary concern, the coefficients of determination result from the structural model requiring uncorrelated errors. Researchers can establish the covariance matrix of the dependent composites, $\Sigma_{\eta\eta}$, as follows:

$$\Sigma_{\eta\eta} = (\mathbf{I} - \mathbf{B})^{-1} \Gamma \Sigma_{\xi\xi} \Gamma' (\mathbf{I} - \mathbf{B}')^{-1} + (\mathbf{I} - \mathbf{B})^{-1} \Sigma_{\zeta\zeta} (\mathbf{I} - \mathbf{B}')^{-1} \tag{4}$$

The computation of $\Sigma_{\eta\eta}$ employs a nonlinear optimization to determine the diagonal matrix $\Sigma_{\zeta\zeta}$ such that the composites have unit variances (Fig. 1).

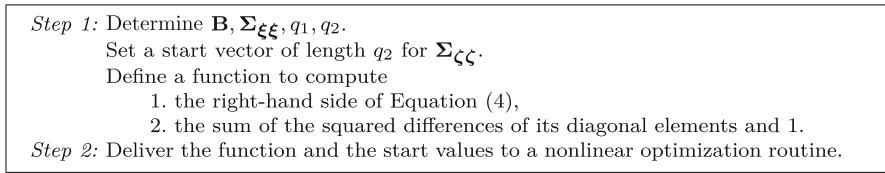


Fig. 1 Nonlinear determination of the matrix $\Sigma_{\zeta\zeta}$

When specifying the dependent composites' coefficients of determination a priori, researchers must determine the path coefficients accordingly. Consider the structural regression equation for the dependent composite η_c given in Eq. (2):

$$\eta_c = \xi \gamma_c + \eta_{1:c-1} \beta'_{c,1:c-1} + \zeta_c, \quad 1 \leq c \leq q_2, \tag{5}$$

Here $\beta_{c,1:c-1}$ is the row vector consisting of the first $c - 1$ elements of row c of \mathbf{B} . $\eta_{1:c-1}$ is the vector of the dependent composites related to rows 1 to $c - 1$ of \mathbf{B} . The coefficients of the composites that do not appear in the regression equation of η_c are zero. These considerations, together with the covariance matrix $\Sigma_{(q_1+c-1), (q_1+d-1)}$ of $(\xi, \eta_{1:c-1})$ and $(\xi, \eta_{1:d-1})$, results in the following equations:

$$\text{Var}(\eta_c) = (\gamma_c, \beta_{c,1:c-1}) \Sigma_{(q_1+c-1), (q_1+c-1)} (\gamma_c, \beta_{c,1:c-1})' + \sigma_{\zeta_c}^2, \tag{6a}$$

$$\text{Cov}(\eta_c, \xi) = (\gamma_c, \beta_{c,1:q_1+c-1}) \Sigma_{(q_1+c-1), q_1}, \tag{6b}$$

$$\text{Cov}(\eta_c, \eta_d) = (\gamma_c, \beta_{c,1:c-1}) \Sigma_{(q_1+c-1), (q_1+d-1)}, \quad 1 \leq d \leq c. \tag{6c}$$

These equations provide the relations required to compute the composites' covariance matrix.

For simulations that focus on the path coefficients in the structural model, no further information is needed. Here, the R^2 depends on the pre-specified structural model relationships. In contrast, one determines \mathbf{B} a priori to obtain a specific vector $\mathbf{r}^2 = (R_1^2, \dots, R_{q_2}^2)$ of the dependent composites' coefficients of determination in the structural model. More specifically, the coefficient of determination for the regression of η_c on $(\xi, \eta_{1:c-1})$, which is based on Eq. (6c), follows with the assumption $\text{Var}(\eta_c) = 1$:

$$R_c^2 = 1 - \sigma_{\zeta_c}^2 = (\gamma_c, \beta_{c,1:c-1}) \Sigma_{(q_1+c-1), (q_1+c-1)} (\gamma_c, \beta_{c,1:c-1})'. \tag{7}$$

One needs to work through matrix \mathbf{B} from row $q_1 + 1$ to the last one in order to modify the path coefficients in a way that they arrive at the desired coefficients of determination. The first part of the covariance matrix is given by $\Sigma_{\xi\xi}$. After the modification of the path coefficients in row $q_1 + c$ of \mathbf{B} , the covariance matrix of the composites must be augmented by row and column c before the coefficients of row $c + 1$ can be modified. Initially, choose the row vector β_{q_1+c} as preferred. Subsequently, this

preliminary value is multiplied by a factor τ , which allows to fulfill Eq. (7):

$$\tau = \sqrt{\frac{R_c^2}{(\boldsymbol{y}_c, \boldsymbol{\beta}_{c,1:c-1}) \boldsymbol{\Sigma}_{(q_1+c-1), (q_1+c-1)} (\boldsymbol{y}_c, \boldsymbol{\beta}_{c,1:c-1})'}} \tag{8}$$

4 The covariance matrix of the models' indicators

4.1 Computation

The covariance matrix of the indicators is used to simulate the model. With a choice of $\boldsymbol{\Sigma}_{\xi\xi}$, the covariance matrix of the \boldsymbol{x} -indicators and the weights \mathbf{W}_1 must be determined so that

$$\boldsymbol{\Sigma}_{\xi\xi} = \mathbf{W}'_1 \boldsymbol{\Sigma}_{xx} \mathbf{W}_1 \tag{9}$$

is fulfilled. This formulation is en par with the general comprehension of composite-based models as formative measurement (Rhemtulla et al. 2020). Several options are available to choose $\boldsymbol{\Sigma}_{xx}$ and the standardized weights, resulting in a given $\boldsymbol{\Sigma}_{\xi\xi}$. For instance, researchers can first deal with each block of indicators of the different exogenous composites separately, which only requires to ensure the standardization of the composites. This means that $\xi_g = \mathbf{x}_g \mathbf{w}_g, \mathbf{w}'_g \boldsymbol{\Sigma}_{x_g x_g} \mathbf{w}_g = 1$ must be fulfilled. One can meet this requirement, for example, by setting $\boldsymbol{\Sigma}_{x_g x_g}$ as the identity matrix and choosing the weights vectors such that $\mathbf{w}'_g \mathbf{w}_g = 1$. In an alternative approach, researchers can choose the covariance matrix arbitrarily and subsequently scale it to fulfill Eq. (9). If the exogenous composites are uncorrelated, one uses $\boldsymbol{\Sigma}_{x_g x_h} = \mathbf{0}$ for $g \neq h$. In contrast, if two composites are correlated, one must appropriately select the correlations between the indicators in the two related blocks of indicators. A straightforward solution uses $\boldsymbol{\Sigma}_{x_g x_h}$ and scales it such that $\mathbf{w}'_g \boldsymbol{\Sigma}_{x_g x_h} \mathbf{w}_h = \sigma_{\xi_g \xi_h}$. Becker et al. (2013) used this approach in their study on latent class analysis in PLS.

In the next step, \mathbf{B} is given, or must be determined according to the given vector \mathbf{r}^2 of the coefficients of determination (Sect. 3). With this information, one can obtain $\boldsymbol{\Sigma}_{\eta\eta}$ as described in Sect. 3. $\boldsymbol{\Sigma}_{yy}$ and the weights \mathbf{W}_2 are determined in the same way as the covariance matrix of the X -indicators, using

$$\boldsymbol{\Sigma}_{\eta\eta} = \mathbf{W}'_2 \boldsymbol{\Sigma}_{yy} \mathbf{W}_2 \tag{10}$$

The covariances of the exogenous and the endogenous composites can be used to determine $\boldsymbol{\Sigma}_{xy}$. First, from Eq. (1) it follows that:

$$\boldsymbol{\Sigma}_{\xi\eta} = \mathbf{W}'_1 \boldsymbol{\Sigma}_{xy} \mathbf{W}_2 \tag{11}$$

whereas Eq. (3) leads to:

$$\boldsymbol{\Sigma}_{\xi\eta} = \boldsymbol{\Sigma}_{\xi\xi} \boldsymbol{\Gamma}' (\mathbf{I} - \mathbf{B}')^{-1} \tag{12}$$

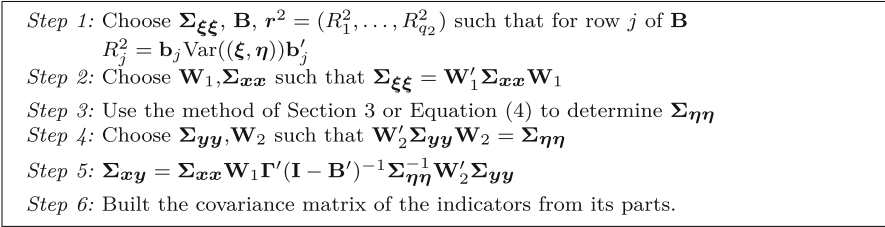


Fig. 2 Setting up the covariance matrices

The combination of these two equations provides a necessary condition that must be fulfilled:

$$\mathbf{W}_1' \Sigma_{xy} \mathbf{W}_2 = \Sigma_{\xi\xi} \Gamma' (\mathbf{I} - \mathbf{B}')^{-1}. \tag{13}$$

Choosing the covariance matrix Σ_{xy} as

$$\Sigma_{xy} = \Sigma_{xx} \mathbf{W}_1 \Gamma' (\mathbf{I} - \mathbf{B}')^{-1} \Sigma_{\eta\eta}^{-1} \mathbf{W}_2' \Sigma_{yy} \tag{14}$$

permits to meet the requirement of Eq. (13). To arrive at this result, it is necessary to insert this expression into the left-hand side of Eq. (13) and to consider the relations for the covariance matrices of the composites. Figure 2 offers a quasi-code for the computation of the covariance matrices of the indicators. Equation (14) ensures that Eq. (13) is fulfilled. In special constellations other solutions may exist for the given matrices $\mathbf{W}_1, \mathbf{W}_2$ and $\Sigma_{\xi\eta}$. In any case, the resulting covariance matrices of the composites are the same. Therefore, a possible non-uniqueness does not affect the estimated results of the structural model.

4.2 Example

In the following, we present an example to illustrate how to establish the covariance matrix of the indicators. We consider the following structural model, which includes three independent and three dependent composites and their three partial regression models with pre-specific coefficients for the data generation propose:

$$(\eta_1, \eta_2, \eta_3) = (\xi_1, \xi_2, \xi_3) \begin{pmatrix} \gamma_{11} & 0 & 0 \\ \gamma_{12} & \gamma_{22} & 0 \\ 0 & \gamma_{23} & 0 \end{pmatrix} + (\eta_1, \eta_2, \eta_3) \begin{pmatrix} 0 & 0 & \beta_{31} \\ 0 & 0 & \beta_{32} \\ 0 & 0 & 0 \end{pmatrix} + (\zeta_1, \zeta_2, \zeta_3).$$

The covariance matrix of the independent composites and the coefficients of determination of the regressions for the independent composites are set to:

$$\Sigma_{\xi\xi} = \begin{pmatrix} 1 & 0.4 & 0.1 \\ 0.4 & 1 & 0.3 \\ 0.1 & 0.3 & 1 \end{pmatrix}, \quad \mathbf{r}^2 = (0.8 \ 0.7 \ 0.6).$$

The pre-specified path coefficients are $\gamma_{11} = \gamma_{22} = 0.6, \gamma_{12} = \gamma_{23} = 0.5, \beta_{31} = \beta_{32} = 0.4$.

The next step in determining the covariance matrix of composites is to recalculate the path coefficients. First, one needs to consider the regression model $\eta_1 = \gamma_{11}\xi_1 + \gamma_{12}\xi_2 + \zeta_1$. Based on $\text{Var}(\eta_1) = \gamma_{11}^2 + \gamma_{12}^2 + 2\gamma_{11}\gamma_{12}\text{Cov}(\xi_1, \xi_2) + \text{Var}(\zeta_1) = 1$ it is possible to obtain $\text{Var}(\zeta_1) = 0.15$. In order to achieve $R_1^2 = 1 - \text{Var}(\zeta_1) = 0.8$ the coefficients γ_{11}, γ_{12} are multiplied by $\tau = \sqrt{0.8/0.85}$. The second regression model $\eta_2 = \gamma_{22}\xi_2 + \gamma_{23}\xi_3 + \zeta_2$ results in $\text{Var}(\zeta_2) = 0.21$. From this, one derives the factor $\tau = \sqrt{0.7/0.79}$. Up to this point the modified path coefficients are: $\gamma_{11} = 0.582, \gamma_{12} = 0.485, \gamma_{22} = 0.565, \gamma_{23} = 0.471$.

Computing the factor of the third regression computation requires researchers to establish the covariance matrix of (ξ, η_1, η_2) . Equations (6a) to (6c) result in:

$$\text{Cov}(\eta_1, \xi) = (0.776 \ 0.718 \ 0.204)$$

$$\text{Cov}(\eta_2, \xi) = (0.273 \ 0.706 \ 0.640)$$

$$\text{Cov}(\eta_1, \eta_2) = (0.565 \ 0.471 \ 0) \begin{pmatrix} 1 & 0.4 & 0.1 & 0.776 \\ 0.4 & 1 & 0.3 & 0.718 \\ 0.1 & 0.3 & 1 & 0.204 \end{pmatrix} \begin{pmatrix} 0 \\ 0.565 \\ 0.471 \\ 0 \end{pmatrix} = 0.501.$$

Based on these covariances, one proceeds as with the first two regressions. This gives the factor $\tau = \sqrt{0.6/0.346}$. Subsequently the matrices Γ and \mathbf{B} are:

$$\Gamma = \begin{pmatrix} 0.582 & 0.485 & 0 \\ 0 & 0.565 & 0.471 \\ 0 & 0 & 0 \end{pmatrix}, \quad \mathbf{B} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0.447 & 0.447 & 0 \end{pmatrix}.$$

Next, the computation of the complete covariance matrix of the composites, again, uses Eqs. (6a) to (6c).

Finally, the indicators' covariance matrix is determined on the basis of previously established parameters. For this purpose, we build on the results already obtained in Step 1 of Fig. 2. For the next Step 2, let

$$\mathbf{K} = \begin{pmatrix} 1 & 0.3 & 0.2 \\ 0.3 & 1 & 0.2 \\ 0.2 & 0.2 & 1 \end{pmatrix}, \quad \Sigma_{xx} = \begin{pmatrix} \mathbf{K} & \mathbf{1} & \mathbf{1} \\ \mathbf{1} & \mathbf{K} & \mathbf{1} \\ \mathbf{1} & \mathbf{1} & \mathbf{K} \end{pmatrix} \quad \text{and} \quad \mathbf{W}_1 = \begin{pmatrix} \mathbf{w}_1 & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{w}_2 & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{w}_3 \end{pmatrix}$$

where $\mathbf{1}$ is a 3×3 matrix of ones, $\mathbf{w}_1 = (0.4, 0.5, 0.6)'$ and $\mathbf{0}$ a vector of zeros.

First, \mathbf{W}_1 has to be standardized. This is done by computing \mathbf{w}_1/\sqrt{f} with $f = \mathbf{w}_1' \mathbf{K} \mathbf{w}_1 = 1.106$, and by substituting the new vector for the old \mathbf{w}_1 . \mathbf{w}_2 and \mathbf{w}_3 are standardized analogously. Subsequently, blocks of ones in Σ_{xx} have to be changed such that the covariances in $\Sigma_{\xi\xi}$ are recovered. For example, to obtain $\sigma_{13} = 0.469$, the ones in the first three rows and the last three columns are modified to $0.469/(\mathbf{w}_1' \mathbf{1} \mathbf{w}_3)$.

Analogously, one obtains the matrix \mathbf{W}_2 by considering $\Sigma_{\eta\eta}$. Finally, Σ_{xy} is computed using Eq. (14). As a result, one receives the complete covariance for data

generation. Based on this covariance matrix follows the data generation as explained in the following section.

5 Data generation

The covariance matrix can be used to generate a dataset for composite model-based simulation studies. This is particularly easy when the indicators are normally distributed. Then a $(n, p_1 + p_2)$ matrix of independent standard normal random variables is generated and multiplied from the right by the Cholesky factor of the covariance matrix. On the other hand, several suggestions exist for generating data from non-normal distributions with pre-specified parameters. For instance, Vale and Maurelli (1983) extended the Fleishman (1978) method to generate multivariate random numbers with specified intercorrelations and univariate means, variances, skewness values, and kurtoses. To begin with, they produce a suitably sized matrix of independent, normally distributed random numbers. Then, they subsequently compute the Fleishman's transformation coefficients and use them an intermediate correlation matrix from the desired indicators' correlation matrix. A principal components factorization allows to obtain the intermediate correlation matrix. The resulting factor is multiplied with the matrix of independent normally distributed random numbers. Finally, the component-wise application of the Fleishman transformation follows to generate the indicator data.

This method was used for a small simulation experiment to compare the estimates of GSCA and PLS. The experiment changes the generated indicator data's levels of skewness $\sqrt{\beta_1}$ and excess kurtosis β_2 . These levels correspond to normal, Laplace, exponential and t_5 -distributions (although the empirical values of the kurtosis are smaller than those of the target ones). We used the model of the example in Sect. 4 to generate 50 samples of size $n = 100$ for each distribution. Schlittgen's (2018) `gscals` (i.e., for GSCA) and `plspath` (i.e., for PLS) implementations have been

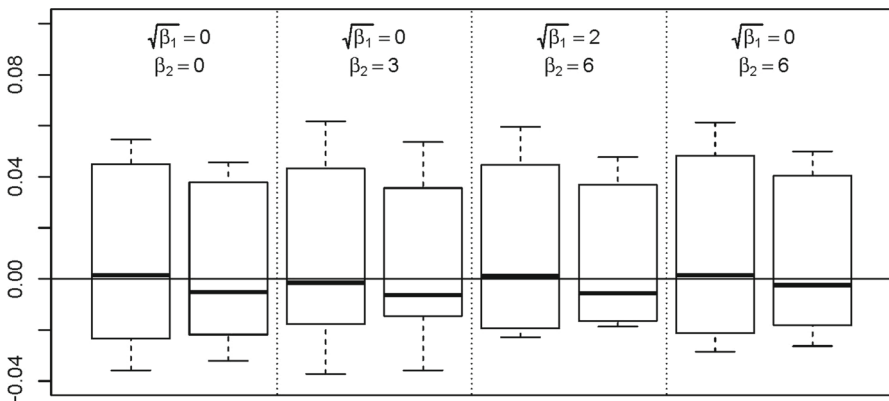


Fig. 3 Deviation of estimated coefficients from model coefficients for different distributions (left: `gscals`, right: `plspath`)

used to obtain the model estimation results. Figure 3 shows the differences between the estimates and the path coefficients used for the simulation.

The results show that the normal data situation does not produce different results compared to the other distributions. Overall, the differences between the two estimation methods' results are marginal. However, the GSCA results are a bit closer to pre-specified value (higher precision) while the PLS estimates are more closely grouped around the pre-specified value (higher robustness).

6 Conclusion

The data generation of pre-specified models is an important issue in composite-based SEM, especially when conducting simulation studies. Reinartz et al. (2002) investigate the simulation of common factor-based models when the latent variables are generated first. This is a sensible approach in these models, but not in composite-based ones since they comprise linear combinations of indicators (Sarstedt et al. 2016). Their distributions, therefore, depend on the distributions of the indicators and will be nearer to the normal distribution if the weights do not deviate strongly from each other.

This article contributes to the literature on SEM by discussing properties of data generation in composite-based models. The pre-specified model parameters allow to obtain the indicators' covariance matrices to be used as input for data generation. Furthermore, we offer an example of nonnormally distributed indicators using Vale and Maurellis' (1983) approach.

Our findings are important for researchers who run simulation studies to compare the efficacy of existing, expanded, and newly developed algorithms for the estimation of composite-based SEM models. Also, researchers who like to analyze methodological extensions for composite-based SEM—such as the efficiency of existing and new segmentation algorithms (e.g., Schlittgen et al. 2016)—will take advantage of this research. Future research should further evaluate our approach, for example, in terms of more extreme forms of nonnormality or multimodal distributions. A promising extension would be to adjust the approach to accommodate nonlinear relationships whose use has gained momentum in applications of composite-based SEM (Sarstedt et al. 2020).

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